

Use of adaptive beamformers in MEG source modeling

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Applications of Beamformers in MEG

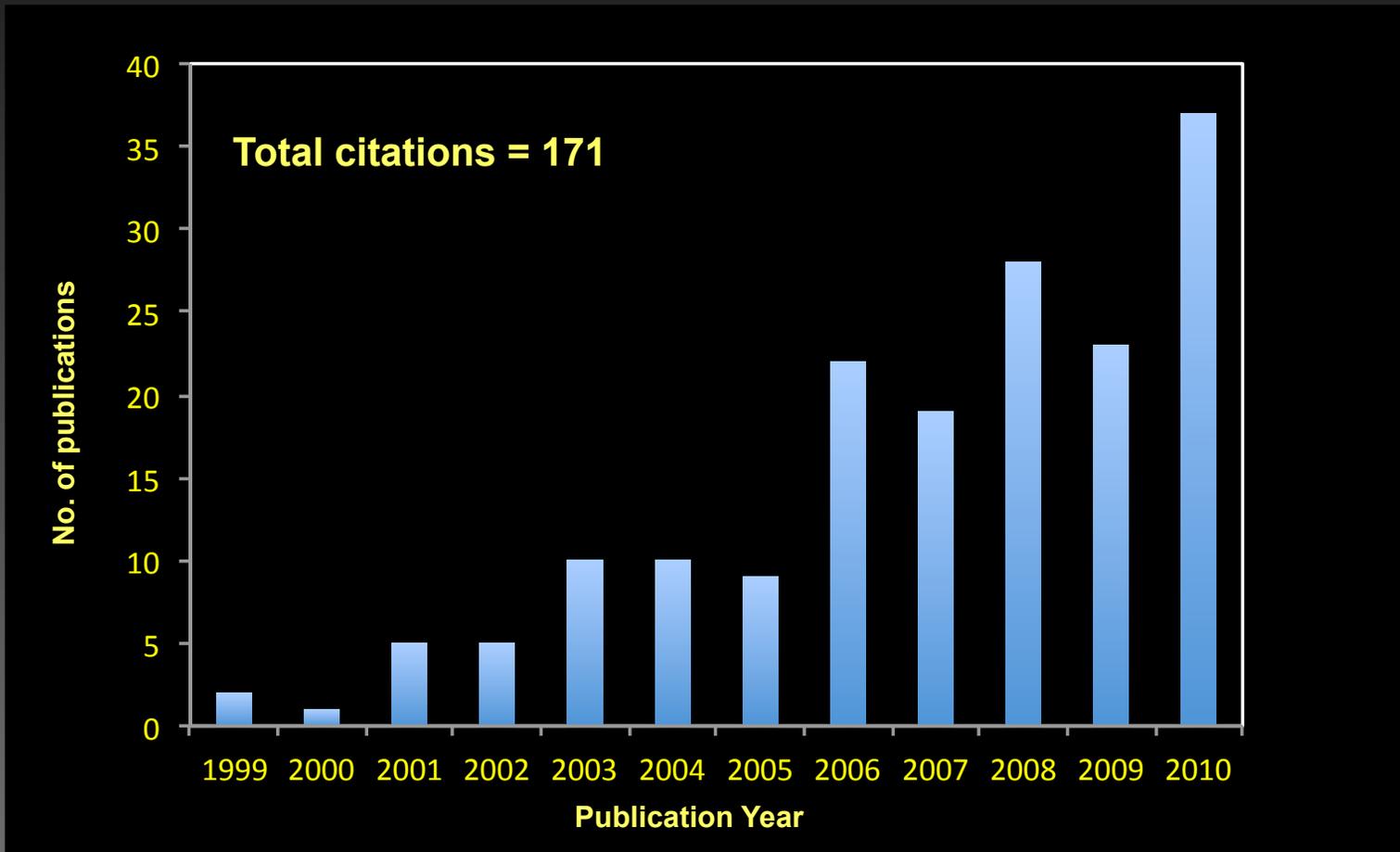
- **Introduction to adaptive beamformers**
- **Advantages and disadvantages of beamformers**
- **Differential vs. event-related imaging**
- **Examples of clinical applications**

Applications of Beamformers in MEG

- **Introduction to adaptive beamformers**
- **Advantages and disadvantages of beamformers**
- **Differential vs. event-related imaging**
- **Examples of clinical applications**

Use of adaptive beamformers in MEG/EEG

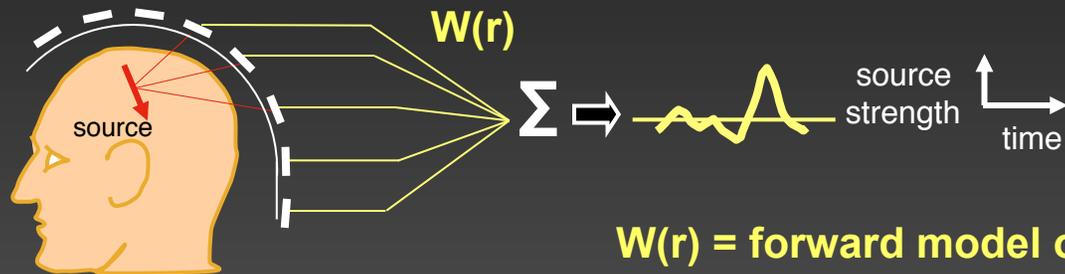
PubMed survey of studies using beamformers and EEG/MEG



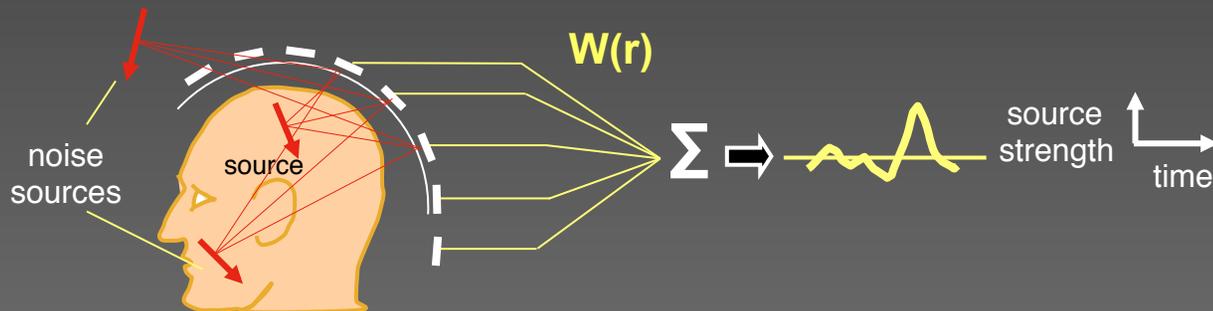
Spatial filtering methods

A spatial filter is the weighted output of the MEG sensor array that reflects activity at a specific brain location over time (i.e., is spatially selective for the target source)

Signal Space Projection (SSP)



Beamformer



Beamformer source models – forward model

Volume based imaging

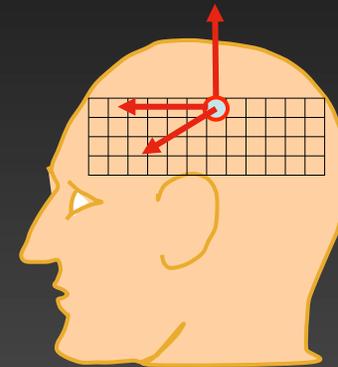
Vector beamformers

- orthogonal current sources at each voxel

E.g.,

Linearly Constrained Minimum-Variance (LCMV) beamformer
(Van Veen et al., 1997)

Vector / eigenspace beamformers
(Sekihara et al., 2001)



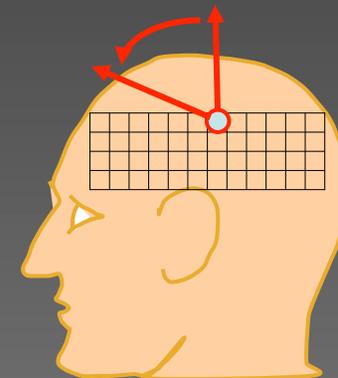
Scalar beamformers

- estimate optimal current direction at each voxel

E.g.,

Synthetic Aperture Magnetometry (SAM)
(Robinson & Vrba, 1999)

Spatiotemporal (event-related) beamformer
(Sekihara et al., 2002; Robinson 2004; Cheyne et al., 2004, 2006)



Beamformer source models – forward model

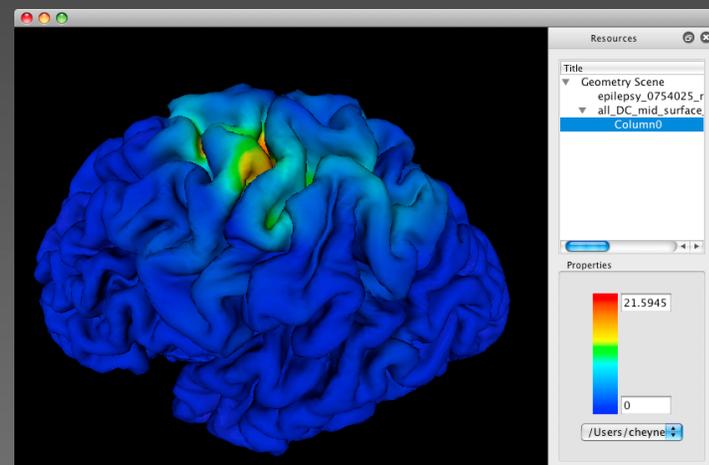
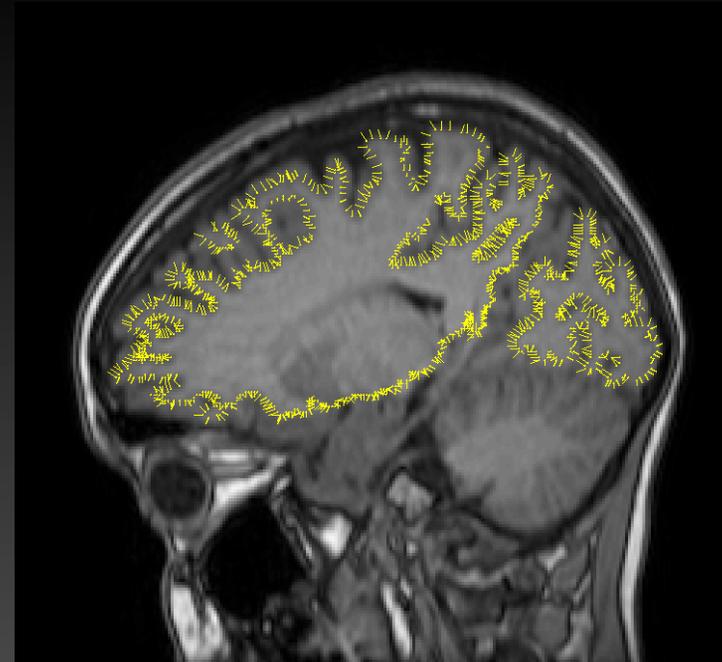
Surface based imaging

Cortically constrained beamformers

- dipole sources normal to cortical surface

Problem:

- Deviation from correct orientation can significantly attenuate output of beamformer (Hillebrand and Barnes, 2003)
- Requires realistic surface, accurate co-registration between MEG and MRI coordinate systems



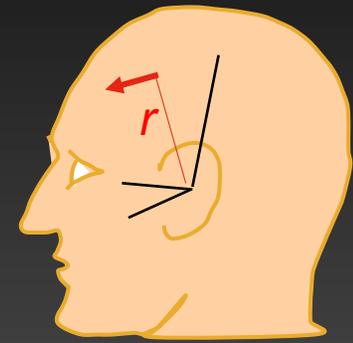
Adaptive (Minimum-variance) Beamforming

Calculation of Spatial Filter:

For location r , define spatial filter as weight matrix, $\mathbf{W}(r)$

Filter output as function of time is measured data vector $\mathbf{m}(t)$ scaled by weights

$$\mathbf{S}(r, t) = \mathbf{W}(r)^T \mathbf{m}(t)$$



Dimensions of $\mathbf{W}(r) = N$ source orientations \times M channels

For scalar beamformer (source has single optimized orientation)

$$\mathbf{s}(r, t) = \mathbf{w}(r)^T \mathbf{m}(t) \quad (\text{"virtual sensor"}) \quad \rightarrow \quad \text{[waveform plot]}$$

Adaptive (Minimum-variance) Beamforming

How do we obtain optimal weights $W(r)$,
when number and location of brain sources are unknown?

Adaptive (Minimum-variance) Beamforming

Total source power emanating from location r over time period T is given by

$$P = \int_T \left\| \mathbf{w}(r)^T \mathbf{m}(t) \right\|^2 dt$$

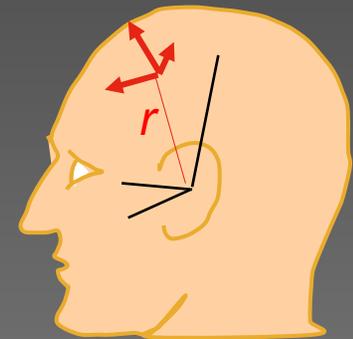
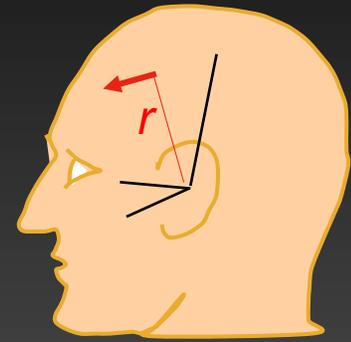
In matrix notation

$$P = \mathbf{w}(r)^T \mathbf{C} \mathbf{w}(r)$$

where $\mathbf{C} = M$ channel \times M sensor covariance matrix

For multi-dimensional weights, signal power is given by

$$P = \text{tr} \left\{ \mathbf{W}(r)^T \mathbf{C} \mathbf{W}(r) \right\}$$



Adaptive (Minimum-variance) Beamforming

To obtain optimal weights, minimize total source power

$$\min_{\{W(r)\}} P = \mathbf{W}(r)^T \mathbf{C} \mathbf{W}(r)$$

subject to constraint (retain unit gain for target forward model):

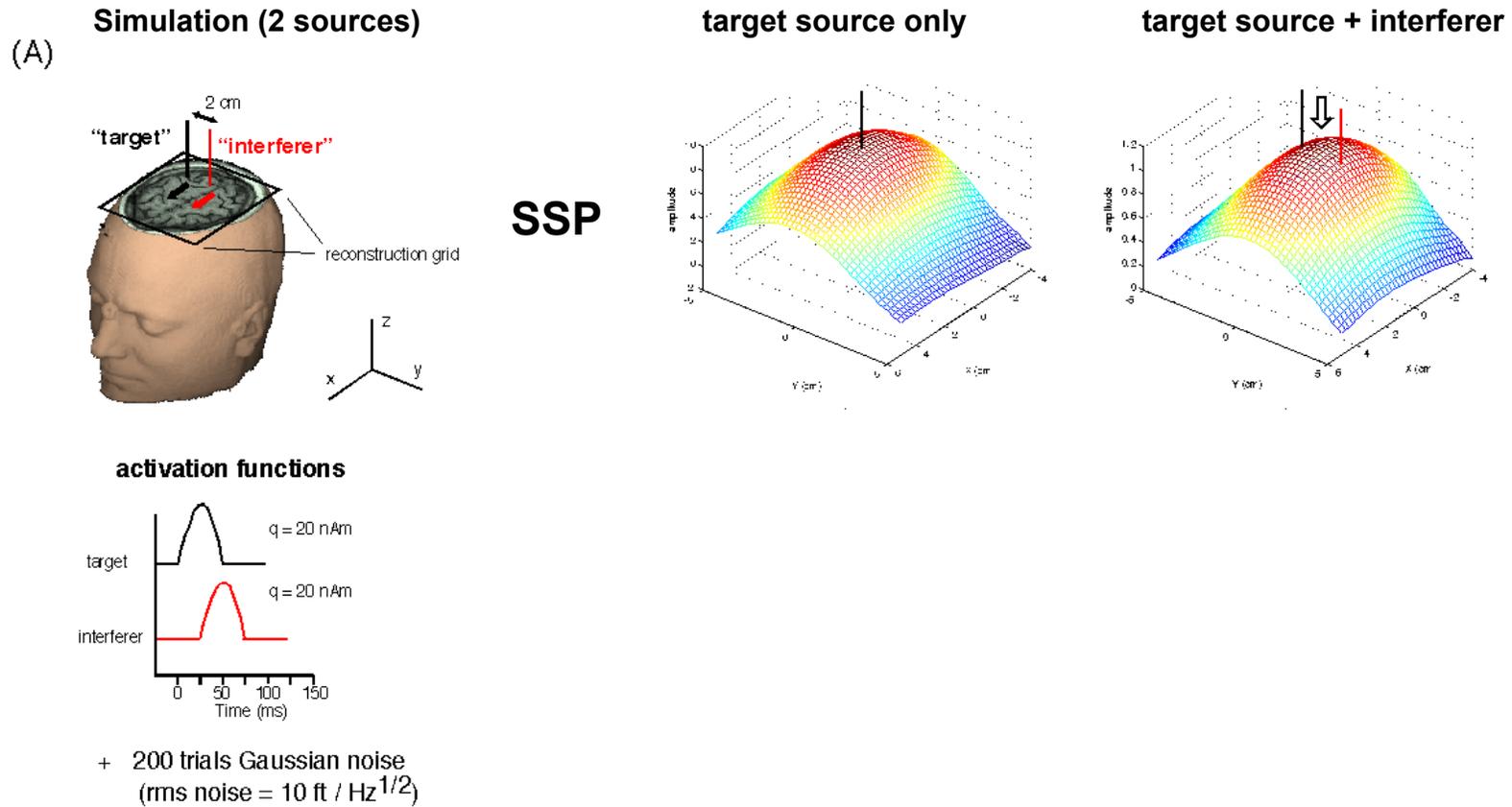
$$\mathbf{W}(r)^T \mathbf{L}(r) = \mathbf{I}$$

where $\mathbf{L}(r)$ = forward solution for current dipole at location r

Solution for weights is given by,

$$\mathbf{W}(r) = \mathbf{C}^{-1} \mathbf{L}(r) \left[\mathbf{L}(r)^T \mathbf{C}^{-1} \mathbf{L}(r) \right]^{-1}$$

Spatial filtering methods – beamforming vs. SSP



Adaptive (Minimum-variance) Beamforming

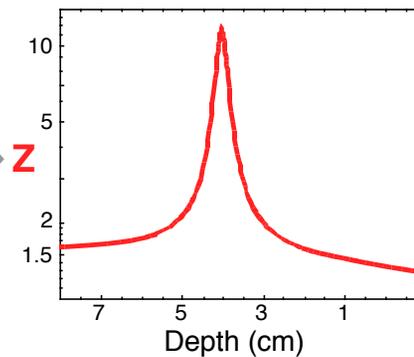
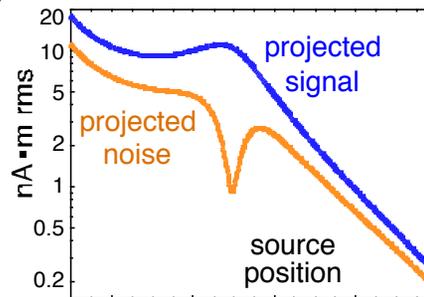
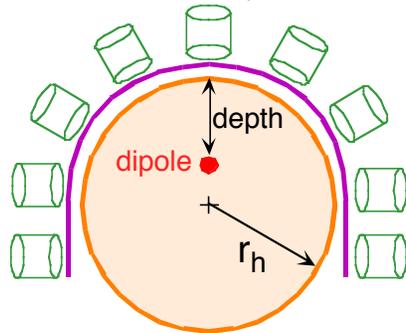
Problem:

Beamformer filter can only suppress noise sources that are correlated across sensors

Uncorrelated noise (e.g., system noise) will be amplified by weights non-linearly with increasing source depth.

Spatial filtering methods – noise based normalization

Simulated case,
 $r_h = 9$ cm, $q = 10$ nA·m rms
Random noise (shielded room)



Projected signal $S^2 = W^T C W$

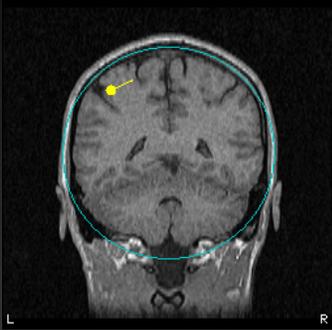
Projected noise $N^2 = W^T \Sigma W$, where Σ = diagonal noise matrix

Ratio = S^2 / N^2

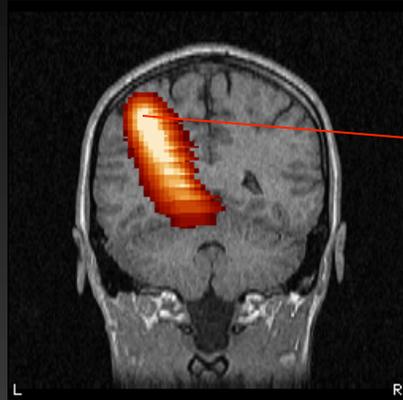
This ratio is also termed “pseudo-Z” (Robinson and Vrba, 1999) or “neural activity index” (Van Veen et al., 1997)

Figure courtesy of J. Vrba

Spatial filtering methods – weight normalization

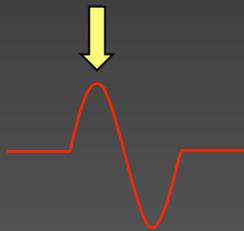
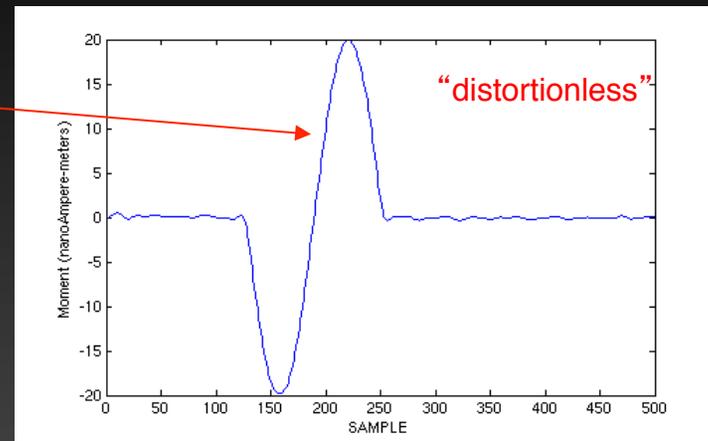


Source location

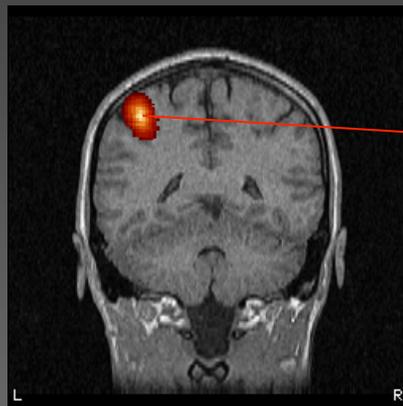


Non-normalized
(units = nA-m)

virtual sensor at peak (nA-m)

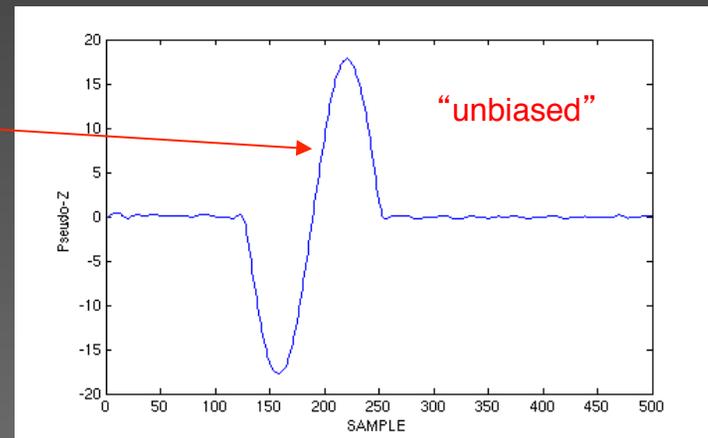


Source activity
(max = 20 nAm)



Normalized
(units = pseudo-Z)

virtual sensor at peak (pseudo-Z)

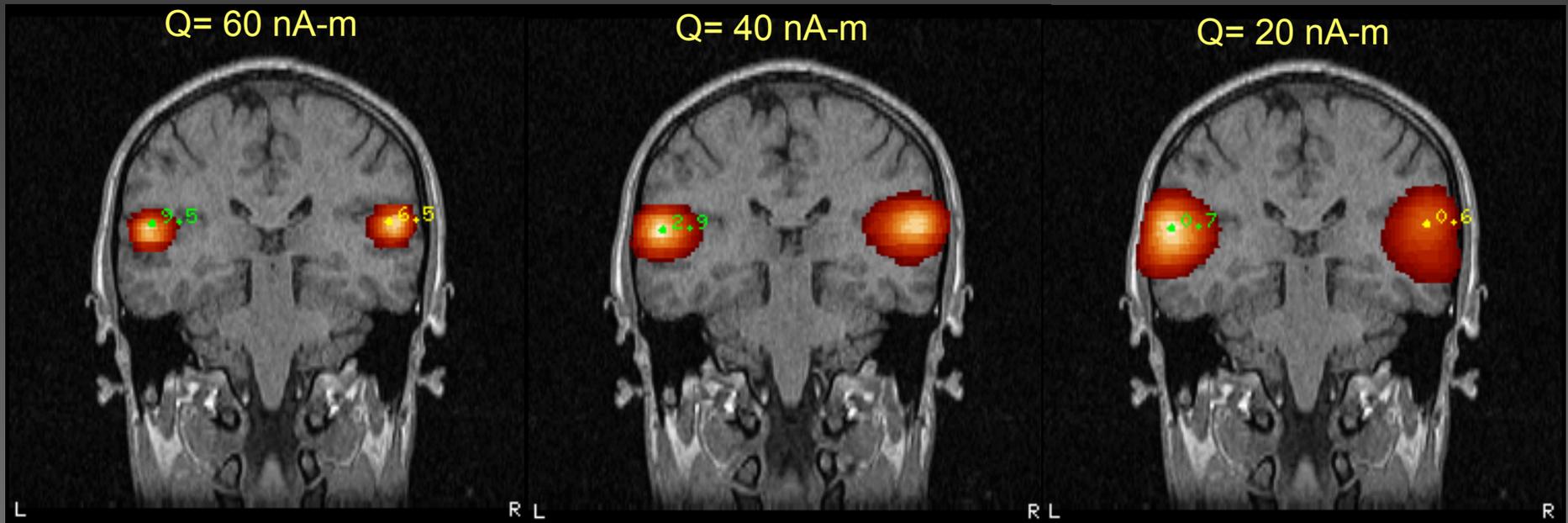
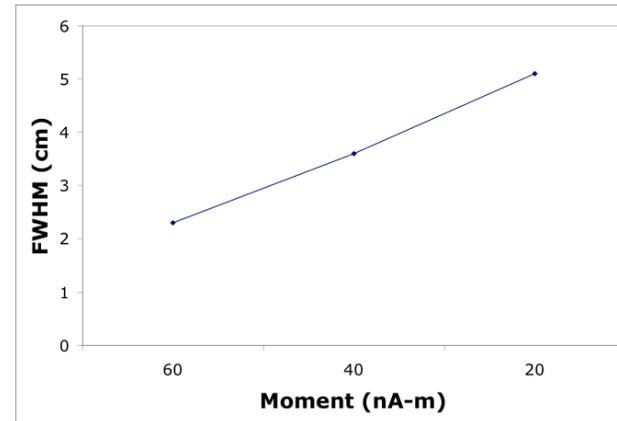


Greenblatt, Ossadtchi & Pflieger, Local linear estimators for the biomagnetic inverse problem. IEEE Trans Signal Proc., 2005

Effect of SNR on beamformer resolution

Simulated bilateral auditory cortex sources

X = 0.0 cm
Y = 5.5 and -5.5 cm
Z = 6.0 cm
+
Gaussian noise

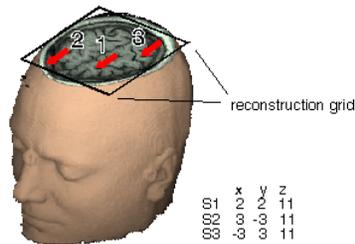


Applications of Beamformers in MEG

- Introduction to adaptive beamformers
- **Advantages and disadvantages of beamformers**
- Differential vs. event-related imaging
- Examples of clinical applications

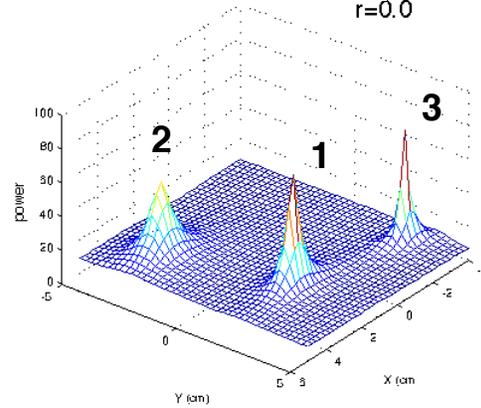
Spatial filtering methods – effects of source correlation

Simulation (3 sources)



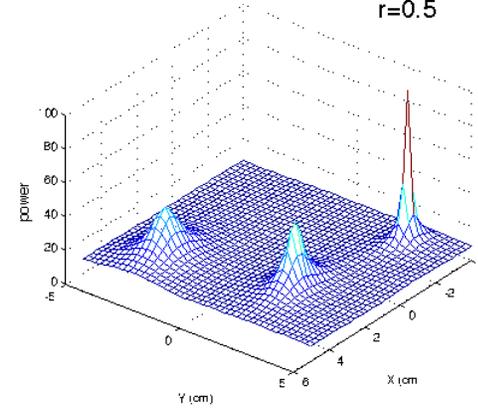
Source power

$r=0.0$

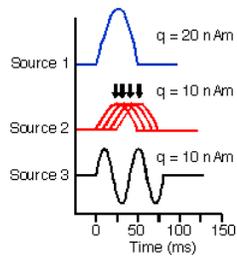


Source power

$r=0.5$



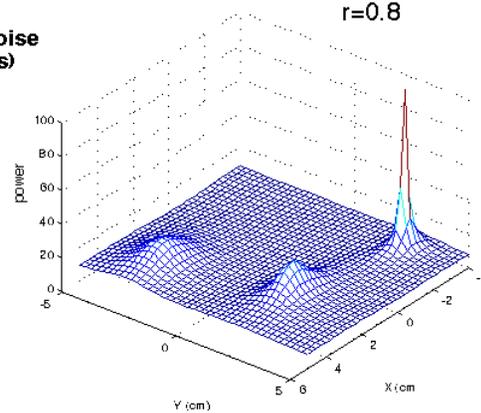
Source activity



+ Gaussian noise
(200 trials)

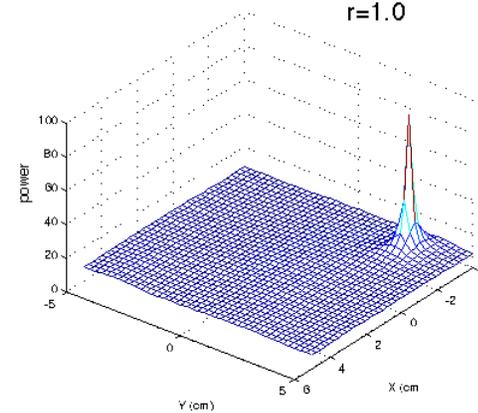
Source power

$r=0.8$



Source power

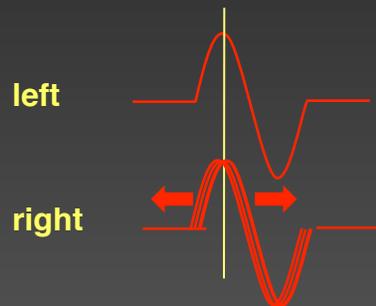
$r=1.0$



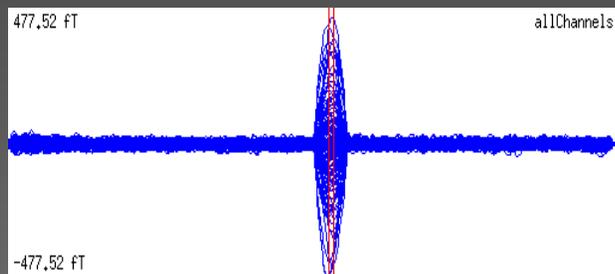
Spatial filtering methods – effects of source correlation

Simulation (auditory evoked fields)

Source 1 (0, 5.5, 6.0)
Source 2 (0, -5.5, 6.0)
Gaussian noise (10 - 20 fT / Hz^{1/2})
150 trials

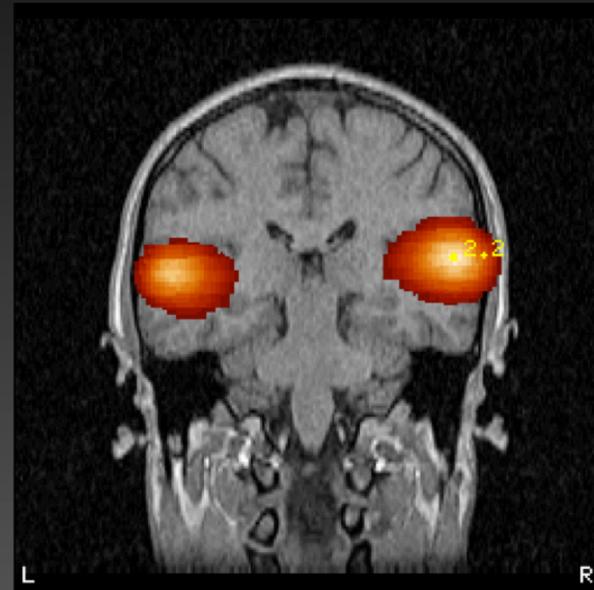


Right hemisphere source
jittered trial-by-trial by 6 ms



Average (all sensors)

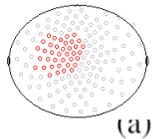
Beamformer source reconstruction



Trial-by-trial latency jitter of 6 ms reduces effect of correlation

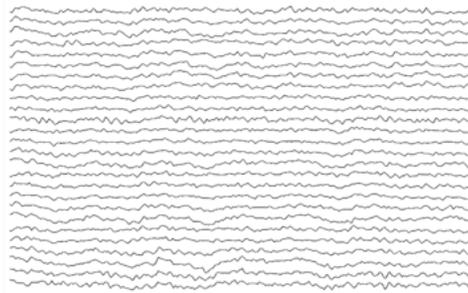
ERB localization with braces motion artifact

151-channel
CTF-MEG



(a)

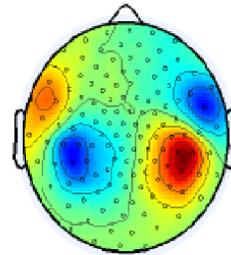
Control
Subject



250 ms | 2.00 pT

Average
(Auditory M100)

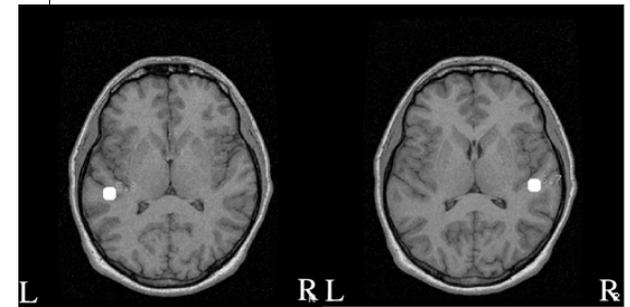
(b)



ERB peak location (M100)

right ear

left ear

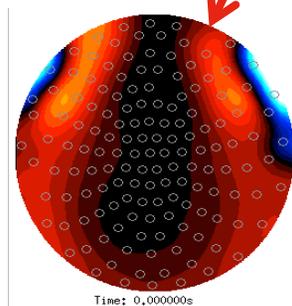
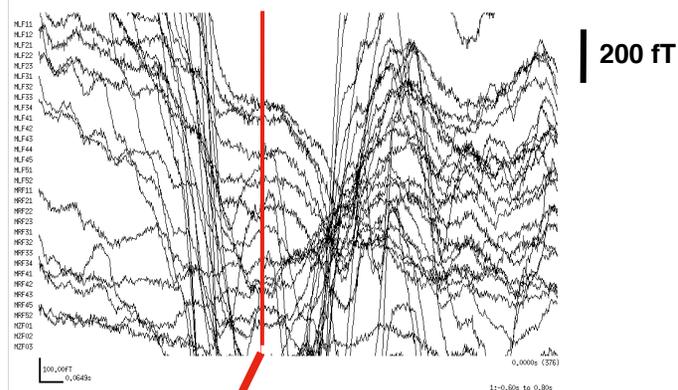


Cheyne, Bostan, Gaetz & Pang (2007)

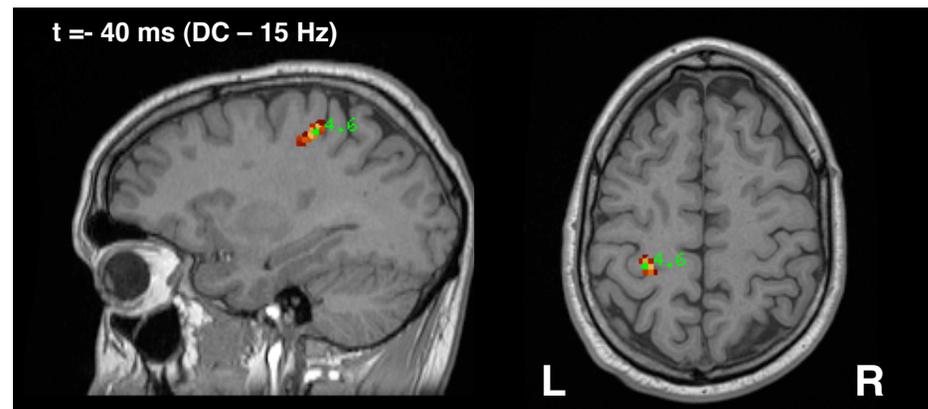
ERB method suppresses ferromagnetic artifacts

Motor Field (MF) localization in subject with metal retainer

Average (frontal sensors)



ERB source image (2 mm)

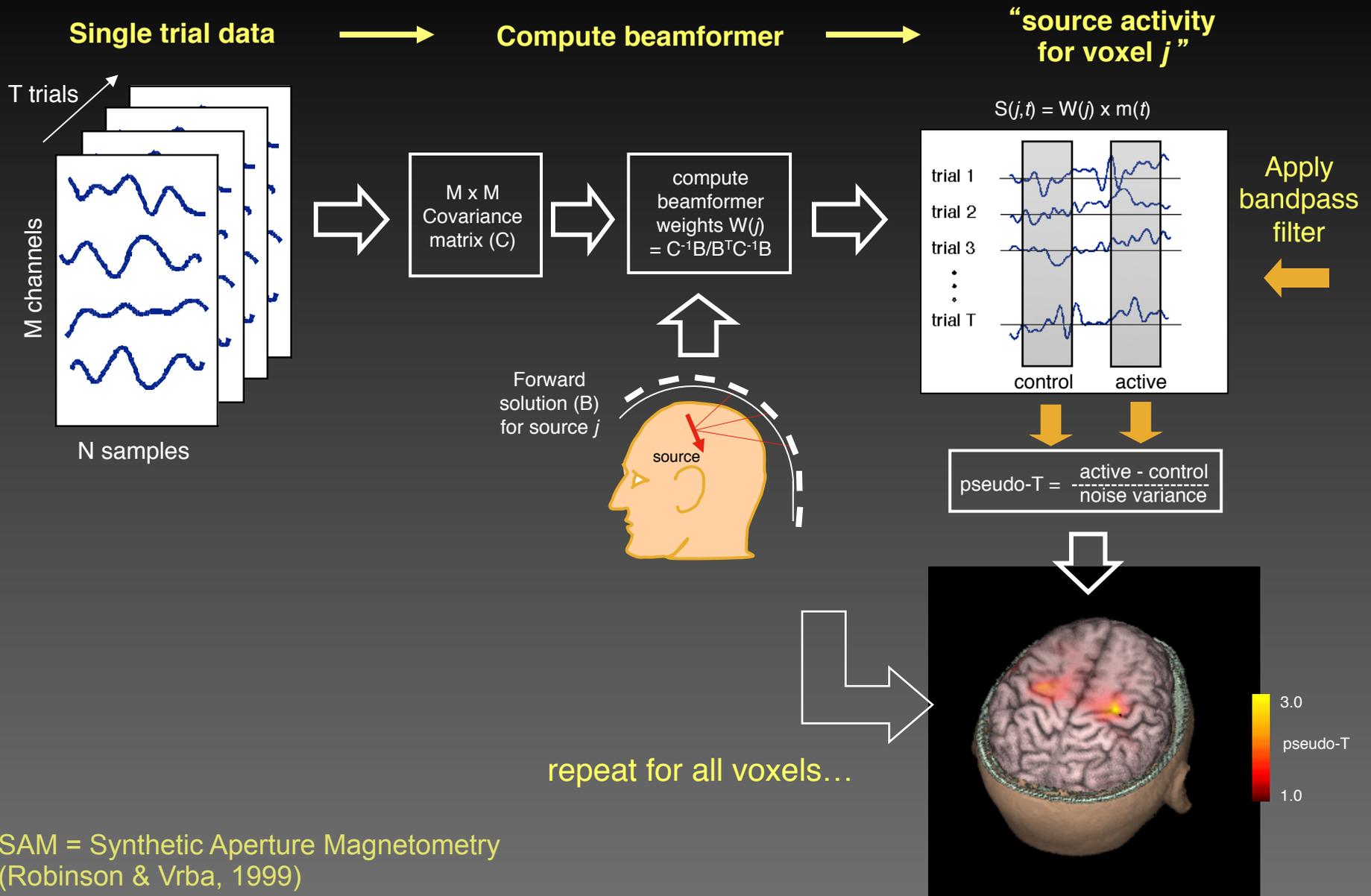


Right index finger movement

Applications of Beamformers in MEG

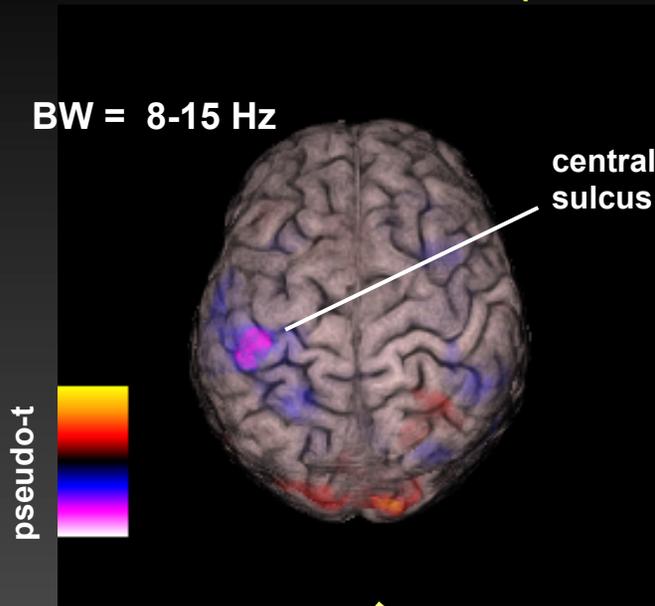
- Introduction to adaptive beamformers
- Advantages and disadvantages of beamformers
- **Differential vs. event-related imaging**
- Applications of beamformers in epilepsy

Differential imaging using the "SAM" beamformer

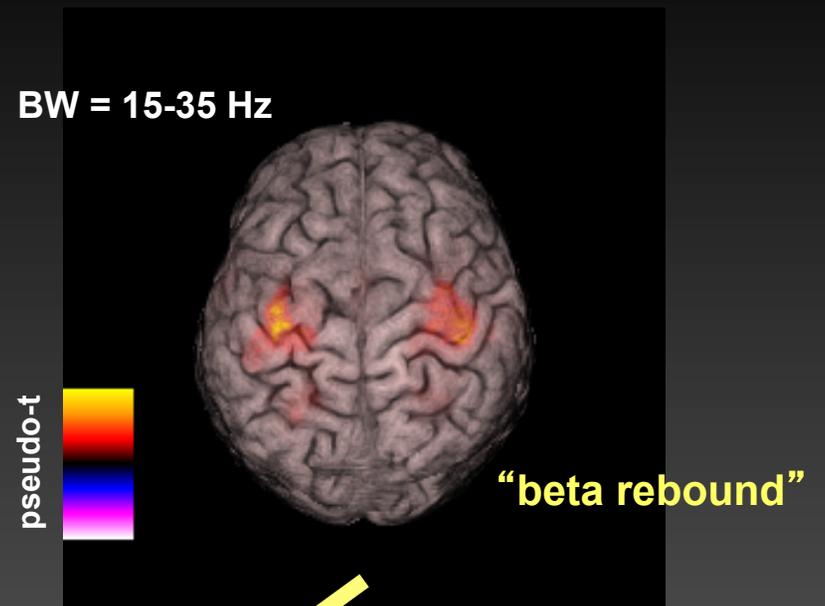


Movement-related mu and beta oscillations

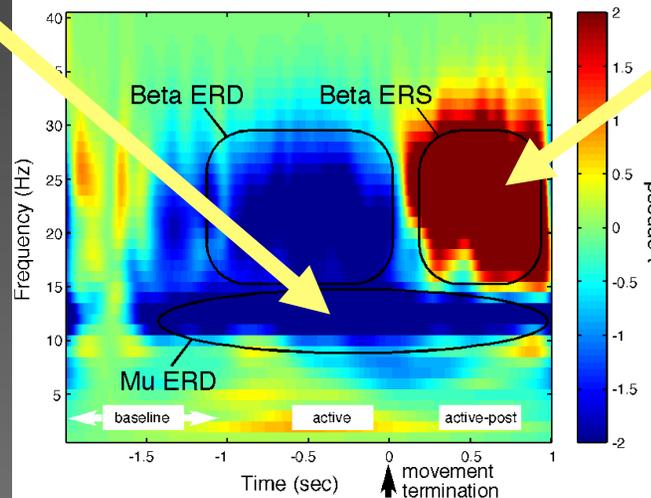
Pre-movement mu (-0.5 to 0 s)



Post-movement beta (0.5 to 1 s)



Contralateral Motor Cortex



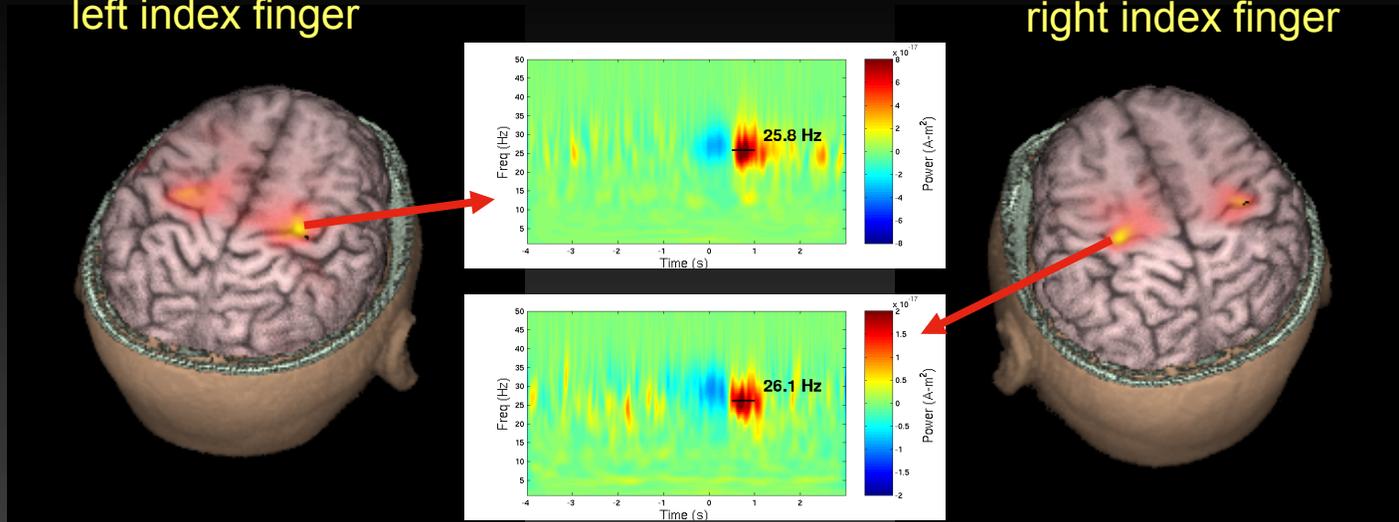
Right index finger movement

Source activity in left sensorimotor cortex

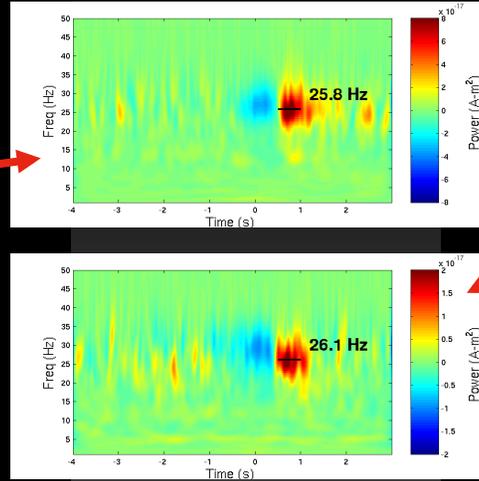
Jurkiewicz, Gaetz,
Bostan & Cheyne,
NeuroImage, 2006

Beta rebound somatotopy

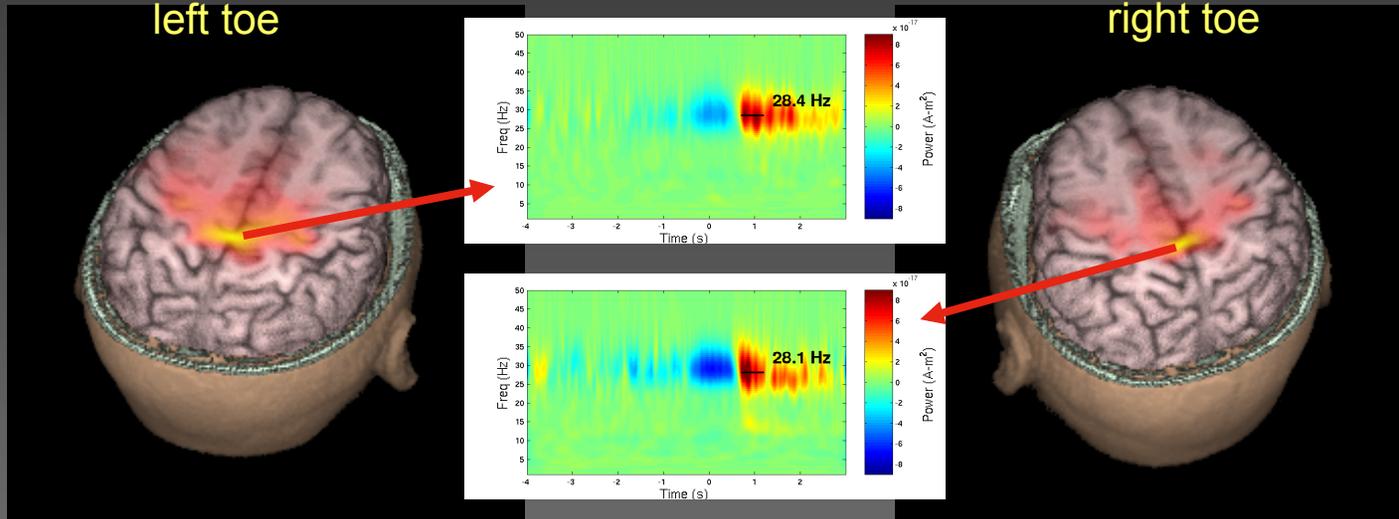
left index finger



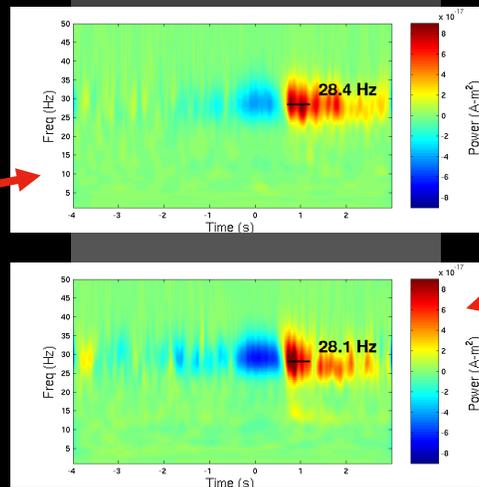
right index finger



left toe

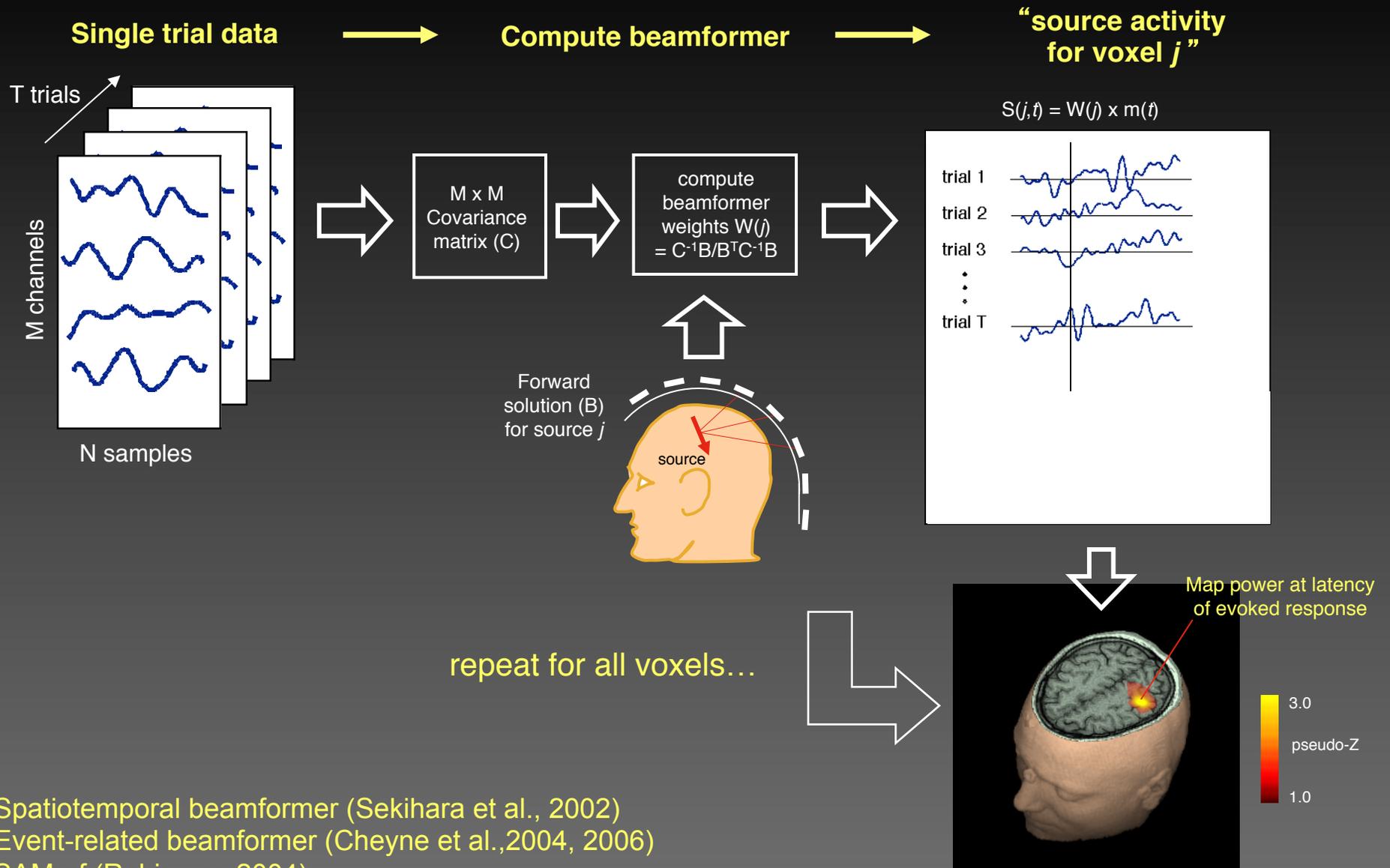


right toe

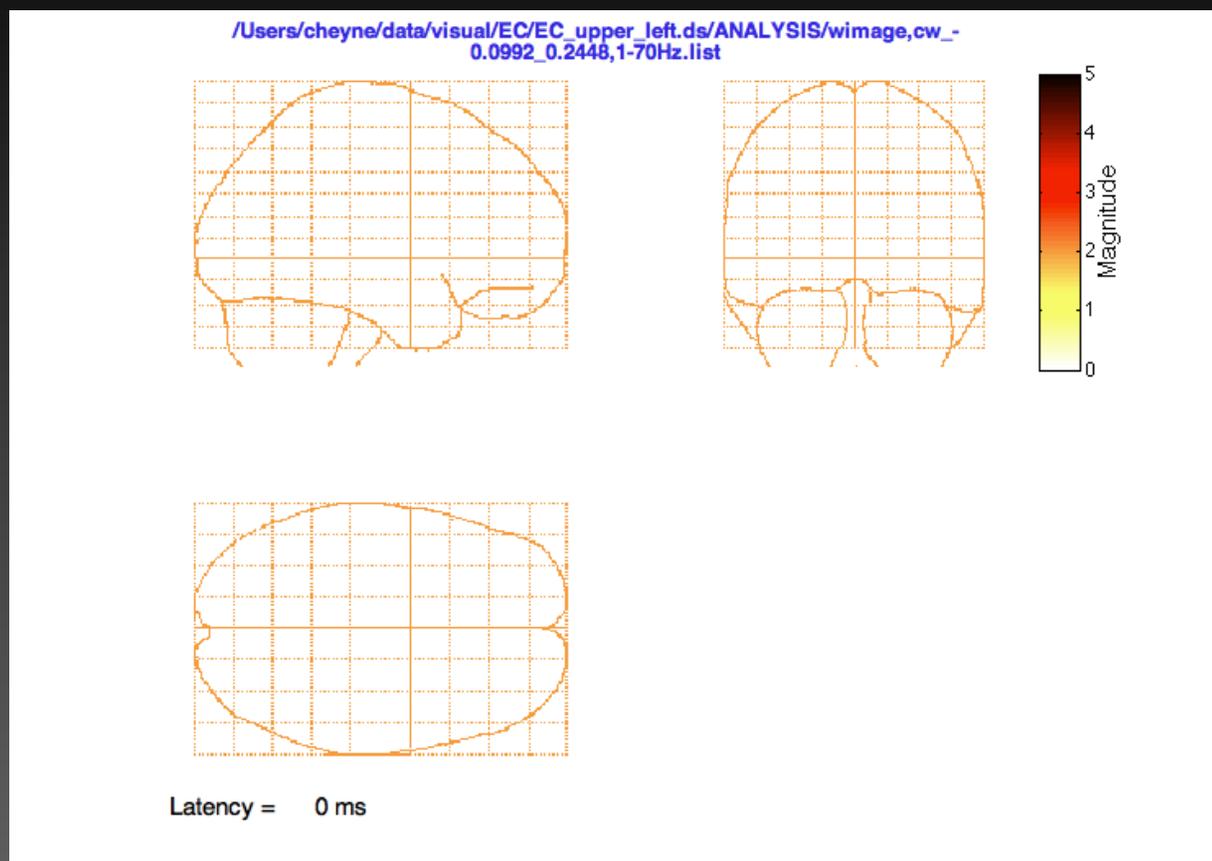


Differential SAM images - rebound period (0.5 - 1 s) minus baseline

Event-related (spatiotemporal) beamformer

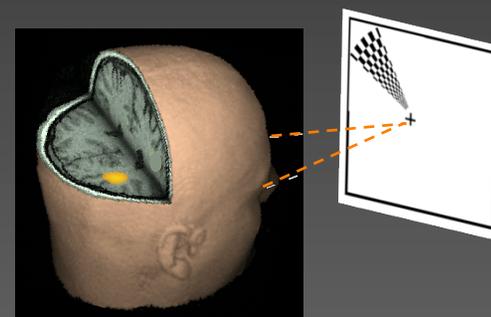


Spatiotemporal beamformer analysis of evoked brain activity



Visual evoked response
(upper left quadrant)

Movie of source images
computed every 1 ms
from 0 to 240 ms



images created with BrainWave toolbox (Cheyne and vanLieshout, 2010)

Applications of Beamformers in MEG

- Introduction to adaptive beamformers
- Advantages and disadvantages of beamformers
- Differential vs. event-related imaging
- **Examples of clinical applications**

MEG at SickKids



11 months



4 year old



18 year old

Children undergoing clinical MEG at Sickkids (2000 – May, 2009)

< 4 years olds (n = 59)
4-8 years olds (n = 165)
9-18 years old (n = 421)
adults (19+) (n = 91)
Total = 736

MEG at SickKids

Clinical applications of MEG at SickKids:

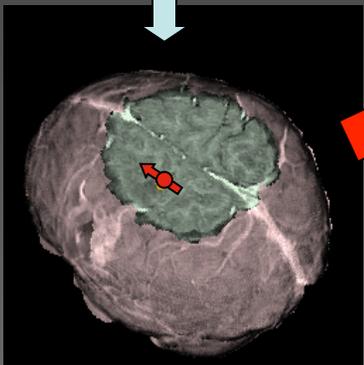
- Surgical planning (epilepsy)
- Presurgical mapping of sensory and motor cortex (e.g., tumour resection)
- Language lateralization (substitute for Wada test)

Presurgical Functional Mapping

Evoked Field

Dipole Fit

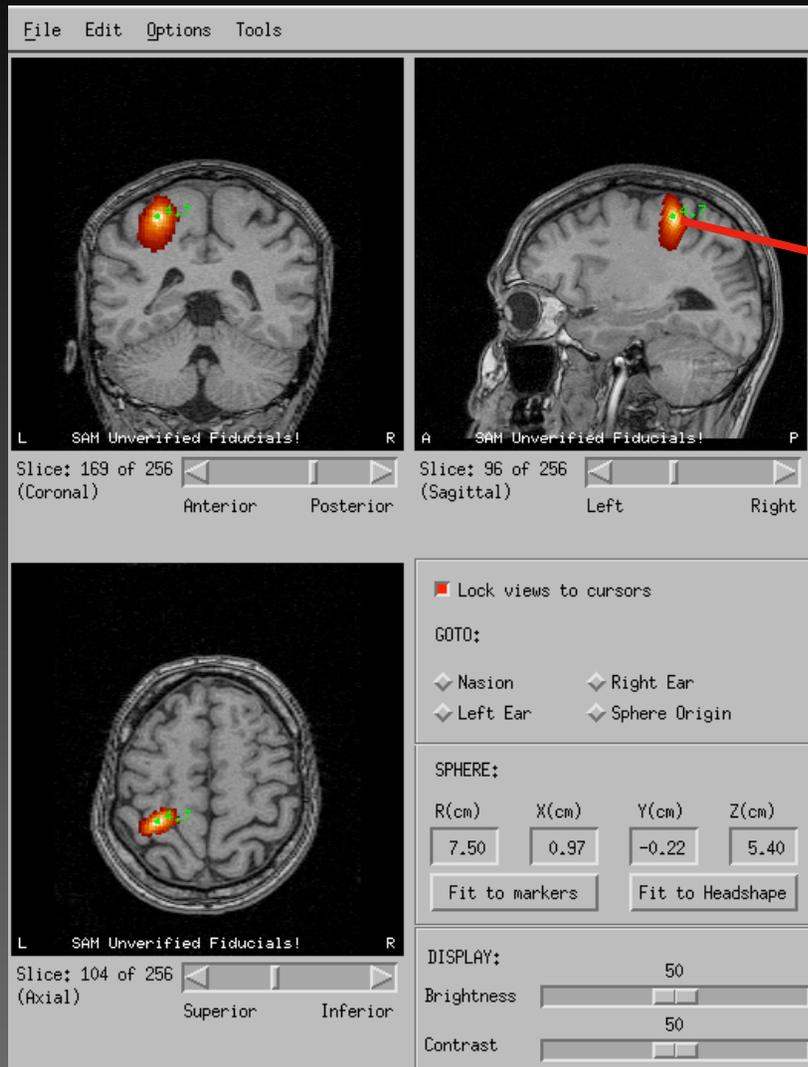
MEG-MRI coreg



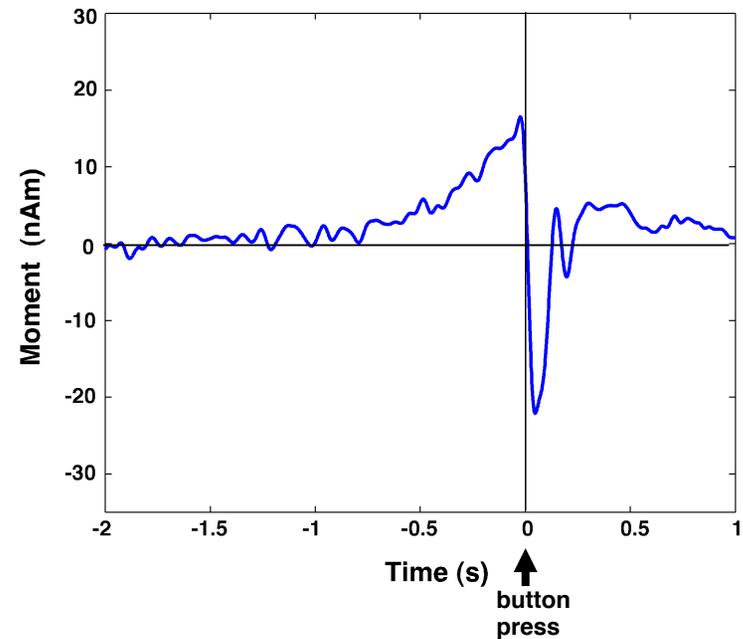
Neuronavigation

The image shows the BrainLAB VectorVision cranial neuronavigation software interface. It features a 2x2 grid of MRI slices: 'Skin Overview' (lateral view of the head), 'Coronal', 'Inline 1', and 'Inline 2'. A yellow 3D model of the brain is visible in the 'Skin Overview' view. A green line with a red dot at the end indicates the 'Pointer -> Target' distance, which is consistently 17.4 mm across all views. The interface includes a control panel on the right with buttons for 'Register', 'Data', 'Tools', 'Acquire', 'Freeze', 'Target', 'Zoom', 'Reset', 'Display', and 'Screenshot'. The software logo 'BrainLAB VectorVision cranial' is visible at the top left of the interface.

Beamformer localization of premovement motor field (MF)



Time course at peak (virtual sensor)



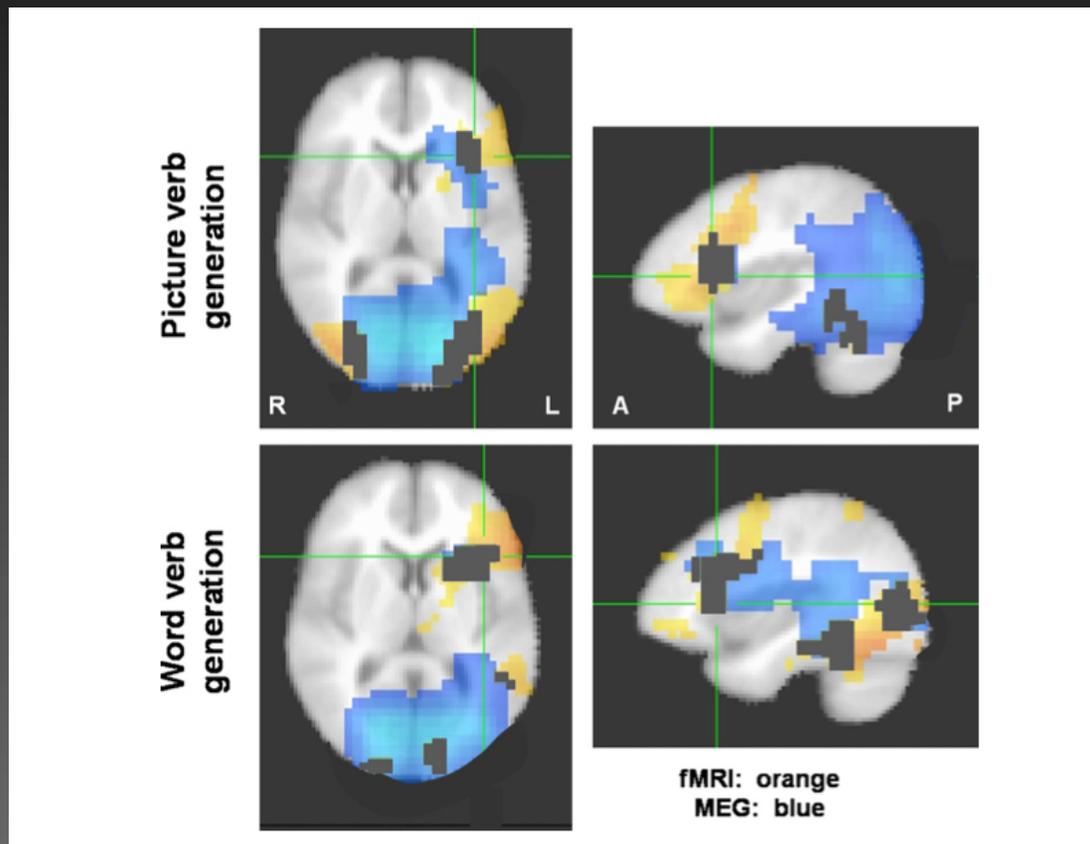
DC-15 Hz

Self-paced right index finger movement
Recording time \approx 10 min (100-130 movements)

ERB image in MRViewer ($t = -40$ ms, threshold = FWHM)

Language lateralization using differential beamformer

Concordance between fMRI and MEG beamformer lateralization of language function (covert picture and word verb generation task)

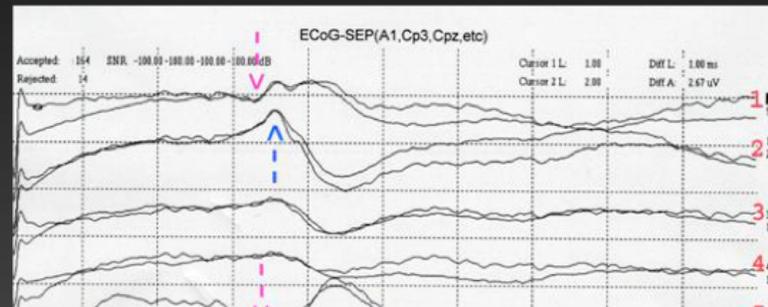
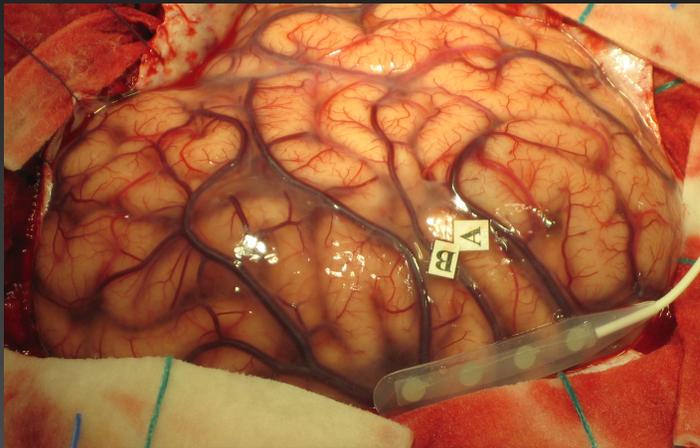


MEG = suppression of source power in beta band localized with SAM beamformer

From Pang, Wang, Malone, Kadis and Donner (2011)

Presurgical Motor Mapping using Beamformers

Intraoperative confirmation using cortical stimulation



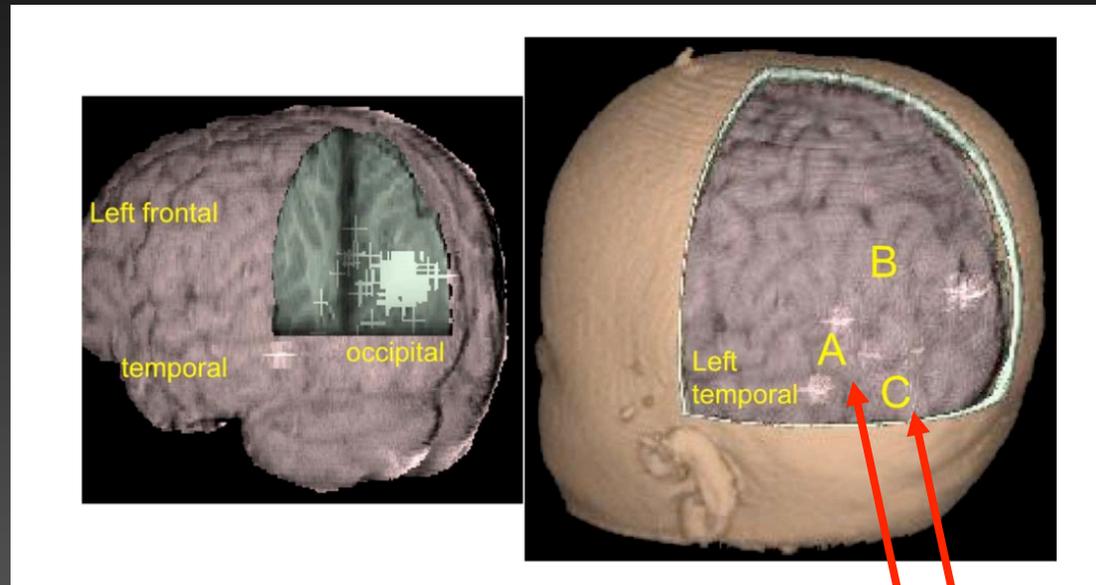
A, MEG SEF
B, MEG motor

- Pang, E.M., Drake, JM., Otsubo H., Martineau A., Strantzas S., Cheyne D., Gaetz W. (2008) Intraoperative confirmation of hand motor area identified preoperatively by magnetoencephalography: A clinical case study. Pediatric Neurosurgery 44:313-317
- Gaetz W., Cheyne D., Drake J., Rutka J., Benifla M., Strantzas S., Widjaja E., Holowka S., Otsubo H., and Pang E.W. (2009) Pre-surgical localization of primary motor cortex in paediatric patients with brain lesions using spatially filtered magnetoencephalography. Neurosurgery 64 (3): 177-186.

Applications of beamformers in epilepsy

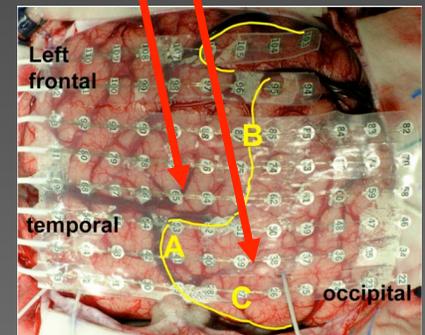
Modeling interictal spikes as single dipoles (dipole clusters)

Co-registration of dipole cluster with patient's MRI



Limitations of dipole fitting approach for epilepsy:

- Low SNR due to lack of signal averaging
- High-amplitude interictal spikes involve large areas of activation



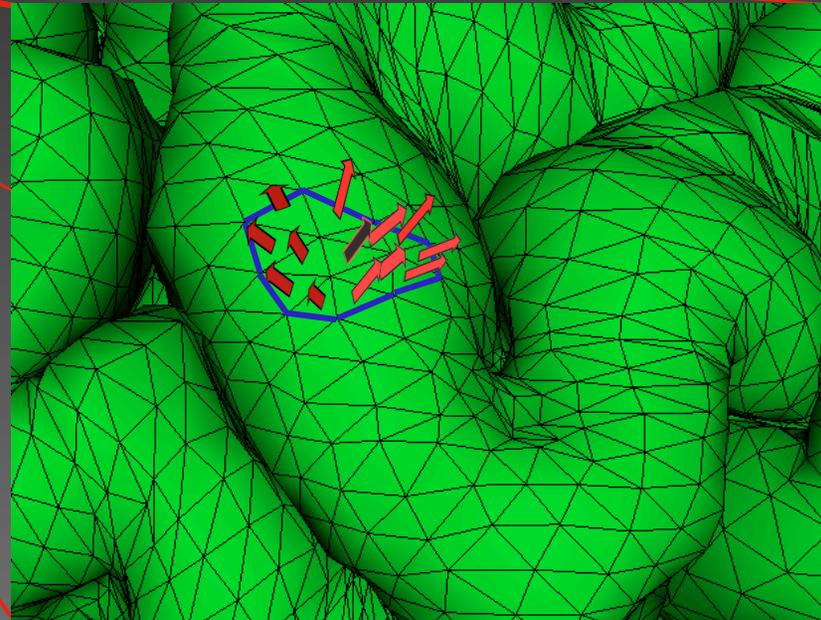
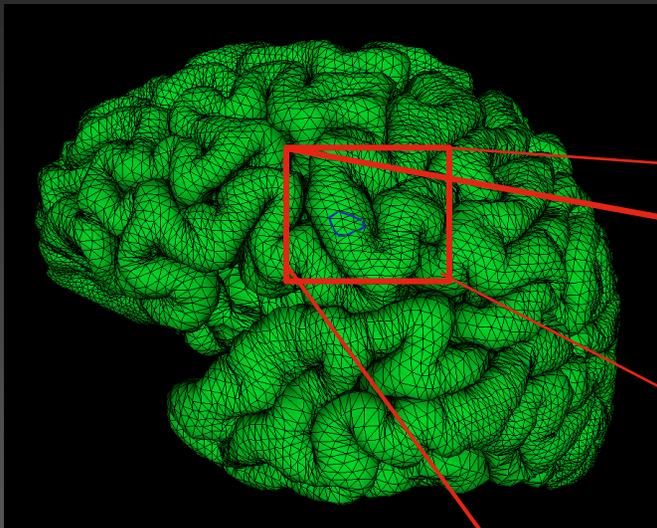
Data courtesy of H. Otsubo, Hospital for Sick Children

Applications of beamformers in epilepsy

Can beamformers image extended sources?

Extended (dipole patch) source

- triangulated mesh ($\approx 80,000$ triangles / hemisphere)*
- patch growing using seed location and neighboring triangles
- uniform current density (0.5 nAm/mm^2)

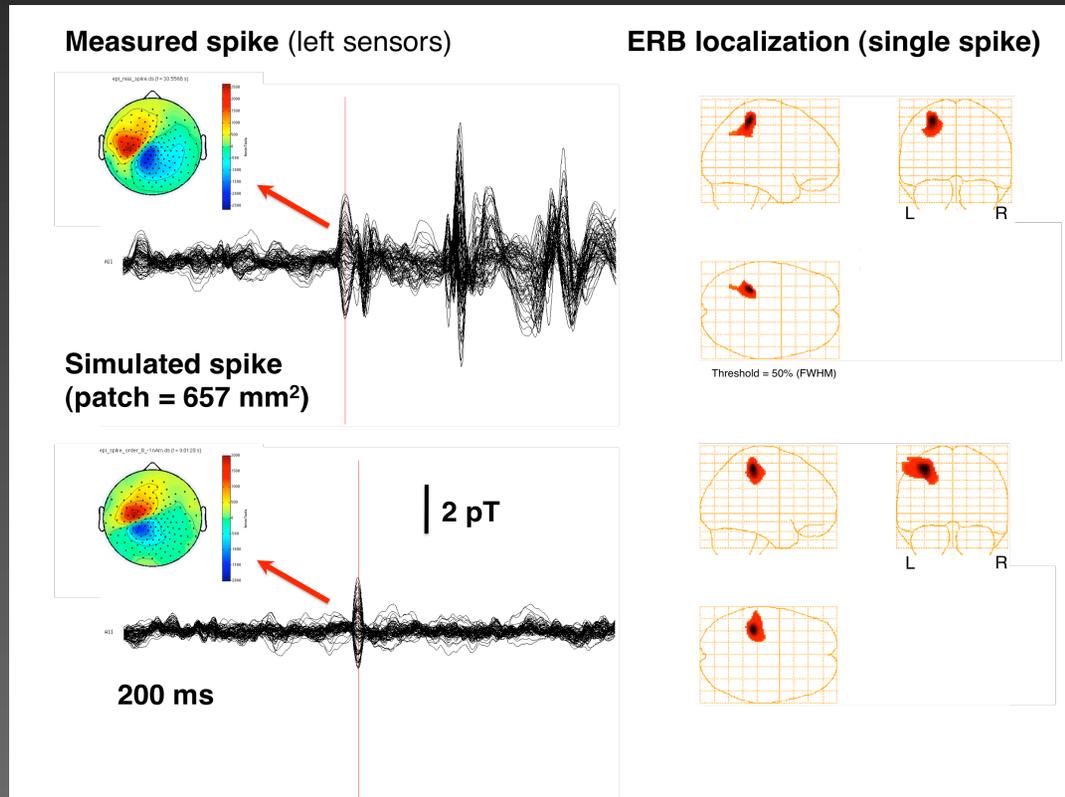


*cortical segmentation courtesy of Dr. Jason Lerch
Mouse Imaging Centre, Toronto Centre for PhenoGenomics

Applications of beamformers in epilepsy

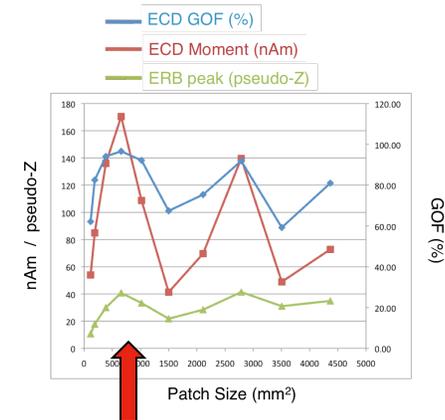
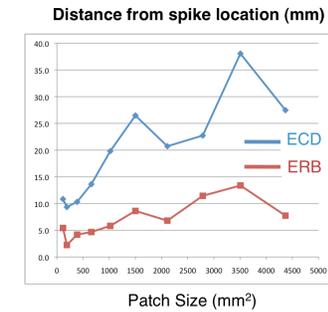
Simulated interictal spike

- data from 12 year-old female patient with right-sided seizures
- dipole coordinates of interictal dipole fit used as seed for patch
- 1.0 nAm/mm² current density
- added to spontaneous activity with no spiking activity
- single 14 s duration trial (BW = 1 – 70 Hz)



Patch simulation parameters

Neighborhood order	# triangles	Total area (mm ²)	Total moment (nAm)
3	73	115	115.3
4	121	189	188.9
6	253	386	385.7
8	433	657	657.0
10	657	1019	1018.8
12	921	1500	1499.5
14	1225	2110	2110.2
16	1569	2787	2786.9
18	1953	3506	3506.3
20	2377	4367	4367.3



Model optimal for approx. 6 cm² patch

Cheyne, Lerch, Mohamed, Ferrari, Lalancette, Pang and Otsubo, (Biomag, 2010)

Acknowledgments:

Cheyne Lab:

Dr. Paul Ferrari
Dr. Natasha Alves
Ze-chuan He
Marc Lalancette
Natascha van Lieshout

Department of Diagnostic Imaging and Division of Neurology (SickKids):

Dr. Liz Pang
Dr. Hiroshi Otsubo
Dr. Ismail Mohamed



